

# PT1164

## Hydrogen Thyratron



The PT1164 is hydrogen-filled tetrode thyatron with ceramic envelope, featuring low jitter and low anode delay time drift. Suitable for use at high pulse repetition rates and in applications requiring ruggedness and compactness. A hydrogen reservoir operating from the heater supply is incorporated.

The PT1164 is particularly recommended for circuits where a high rate of rise of anode current is required.

### ELECTRICAL

Peak Forward Anode Voltage .....	12	kV max
Peak Anode Current .....	350	A max
Average Anode Current .....	500	mA max
Anode Heating Factor .....	$7.0 \times 10^9$	V.A.p.p.s. max
Peak Output Power .....	2.1	MW max
Cathode (Connected internally to one end of heater) .....		oxide coated
Cathode Heater Voltage .....	$6.3 \pm 7.5\%$	V
Cathode Heater Current .....	7.5	A
Reservoir Heater Voltage (See Notes 1) .....	$6.3 \pm 7.5\%$	V
Reservoir Heater Current .....	1.5	A
Tube Heating Time (minimum) .....	3.0	min

### MECHANICAL

Seated Height .....	3.000 inches (76.20 mm) max
Clearance Required Below Mounting Flange .....	1.250 inches (31.75 mm) min
Overall Diameter (mounting flange) .....	2.438 inches (61.91 mm) max
Net Weight .....	10 ounces (284 g) approx.
Mounting Position (See Note2) .....	Any
Tube Connections .....	See Outline
Cooling .....	Natural, Forced-air or Liquid

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**P E N T A   L A B O R A T O R I E S**  
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**ELECTRON TUBES FOR INDUSTRY**



**COOLING**

Where natural cooling is insufficient to maintain the envelope temperatures below the specified rated values, cooling by forced-air, or by oil or coolant immersion may be used.

The temperature of the anode terminal and the base, measured at the points indicated on the outline drawing, must not exceed the values specified below.

Anode Terminal .....	250°	C	max
Base .....	220°	C	max

**PULSE MODULATOR SERVICE**

**MAXIMUM AND MINIMUM RATINGS (Absolute values)**

**Anode**

	<b>Min</b>	<b>Max</b>	
Peak Forward Anode Voltage (See Note 3) .....	-	12	kV
Peak Inverse Anode Voltage (See Note 4) .....	-	12	kV
Peak Anode Current .....	-	350	A
Average Anode Current .....	-	500	mA
Rate of Rise of Anode Current (See Notes 5 and 6) .....	-	10	kA/μs
Anode Heating Factor .....	-	7.0 x 10 <sup>9</sup>	V.A.p.p.s.

**Grid 2**

Unloaded Grid 2 Drive Pulse Voltage (See Note 7) .....	200	750	V
Grid 2 Pulse Duration .....	1.0	-	μs
Rate of Rise of Grid 2 Pulse (See Notes 6) .....	10	-	kV/μs
Grid 2 Pulse Delay .....	0.5	3.0	Tμs
Peak Inverse Grid 2 Voltage .....	-	200	V
Loaded Grid 2 Bias Voltage (See Note 8) .....	-50	-200	V
Forward Impedance of Grid 2 Drive Circuit .....	100	1000	Ohm

**Grid 1 - D.C. Primed (See Note 9)**

D.C. Grid 1 Unloaded Priming Voltage .....	75	150	V
D.C. Grid 1 Priming Current .....	50	150	mA

**Grid 1 - Pulsed**

Unloaded Grid 1 Drive Pulse Voltage (See Note 7) .....	300	750	V
Grid 1 Pulse Duration .....	2.0	-	μs
Rate of Rise of Grid 1 Pulse (See Note 6) .....	1.0	-	kV/μs
Peak Inverse Grid 1 Voltage .....	-	200	V
Loaded Grid 1 Bias Voltage .....	See Note 10		
Peak Grid 1 Drive Current .....	0.15	0.5	A



	<b>Min</b>	<b>Max</b>	
<b>Cathode</b>			
Heater Voltage .....	6.3 ± 7.5%		V
Heating Time .....	3.0	-	min
<b>Reservoir</b>			
Heater Voltage (See Note 1) .....	6.3 ± 7.5%		V
Heating Time .....	3.0	-	min
<b>Environmental (See Note 11)</b>			
Ambient Temperature .....	-55°	+130°	C
Altitude .....	-	10,000	ft
	-	3	km

**CHARACTERISTICS**

	<b>Min.</b>	<b>Typical</b>	<b>Max.</b>	
Critical D.C. Anode Voltage for Conduction .....	-	0.2	0.3	kV
Anode Delay Time .....	-	150	250	ns
Anode Delay Time Drift (See Note 14) .....	-	20	50	ns
Time Jitter (See Note 15) .....	-	1.0	5.0	ns
Cathode Heater Current (at 6.3 V) .....	6.2	7.5	8.8	A
Reservoir Heater Current (at 6.3 V) .....	1.2	1.5	1.8	A

**Notes**

1. The reservoir heater supply must be obtained either from the cathode heater supply or if a separate supply is used it must be decoupled to avoid damage to the reservoir.
2. The tube must be mounted by means of its mounting flange.
3. The maximum permissible peak forward voltage for instantaneous starting is 7.0 kV and there must be no overshoot.
4. The peak inverse voltage including spike must not exceed 5.0 kV for the first 25 μs after the anode pulse.
5. For single shot or burst mode applications this parameter can exceed 100 kA/μs. The ultimate value which can be attained depends to a large extent upon the external circuit.
6. This rate of rise refers to that part of the leading edge of the pulse between 25% and 75% of the pulse amplitude.
7. Measured with respect to cathode. When grid 1 is pulse driven, the last 0.25 μs of the top of the grid 1 pulse must overlap the corresponding first 0.25 μs of the top of the delayed grid 2 pulse.
8. The tube may be operated with a loaded grid 2 bias voltage of 0 to -50 V provided that care is taken to ensure that the peak grid 1 drive current is sufficiently low to prevent triode firing (tube control by the grid 1 pulse).
9. When D.C. priming is used on grid 1, a negative bias of 100 to 200 V must be applied to grid 2 to ensure anode voltage hold-off.
10. D.C. negative bias voltages must not be applied to grid 1. When grid 1 is pulse driven, the potential of grid 1 may vary between -10 and +5 V with respect to cathode potential during the period between the completion of recovery and the commencement of the succeeding grid pulse.



11. To ensure a high standard of ruggedness, all tubes are subjected to the following tests. After each mechanical test all the tubes must then satisfy all electrical tests.
  - (a) Vibration - The tubes are vibrated at 50 Hz with acceleration of 10 g for one minute in the direction of the cathode axis and then in one direction perpendicular to the cathode axis. See note 2.
  - (b) Recovery Time - The tubes are tested for recovery at zero grid 2 bias voltage with a maximum limit of 35  $\mu$ s. The tubes are subjected to the following tests on a sampling basis.
    - (c) Operation under Vibration - The tubes are vibrated at 10 g in each of three planes at a sweep rate of one octave per minute from 20 to 500 to 20 Hz, under normal operating conditions. See note 2.
    - (d) Survival under Vibration and Heater Cycling - The tubes are vibrated a 10 g at a sweep rate of one octave per minute from 5 to 500 Hz for 70 hours in each plane together with heater cycling of a 10 minute on/off cycle. See note 2.
    - (e) Long Duration Shock - The tubes are tested at 125 g for 10 ms with two blows in each plane. See note 2.
    - (f) High Temperature Test - The tubes are tested at a base temperature of 220° C and an anode temperature of 250° C under normal operating conditions for 5 hours. This implies an ambient temperature of 130° C.
    - (g) Low temperature Instant Start - The tubes are cooled to -20° C and subjected to a 3-minute warm up period with 5.8 V on the heater. The tubes must withstand a snap start at 10 kV and operate satisfactorily.
    - (h) Standby-Life - The tubes are run with 6.3 V heater voltage applied for 500 hours.
12. Typical figures are obtained on test using conditions of minimum grid drive. Improved performance can be expected by increasing grid drive.
13. The time interval between the instant when the unloaded grid 2 voltage passes cathode potential and the instant when anode conduction takes place.
14. The drift in delay time over a period from 10 seconds to 10 minutes after reaching full voltage.
15. The recovery characteristics are controlled on a sampling basis.

## **HEATH AND SAFETY HAZARDS**

Penta hydrogen thyatrons are safe to handle and operate, provided that the relevant precautions stated herein are observed. Penta does not accept responsibility for damage or injury resulting from the use of electronic devices it produces. Equipment manufacturers and users must ensure that adequate precautions are taken. Appropriate warning labels and notices must be provided on equipments incorporating Penta devices and in operating manuals

### **High Voltage**

Equipment must be designed so that personnel cannot come into contact with high voltage circuits. All high voltage circuits and terminals must be enclosed and fail-safe interlock switches must be fitted to disconnect the primary power supply and discharge all high voltage capacitors and other stored charges before allowing access. Interlock switches must not be bypassed to allow operation with access doors open.

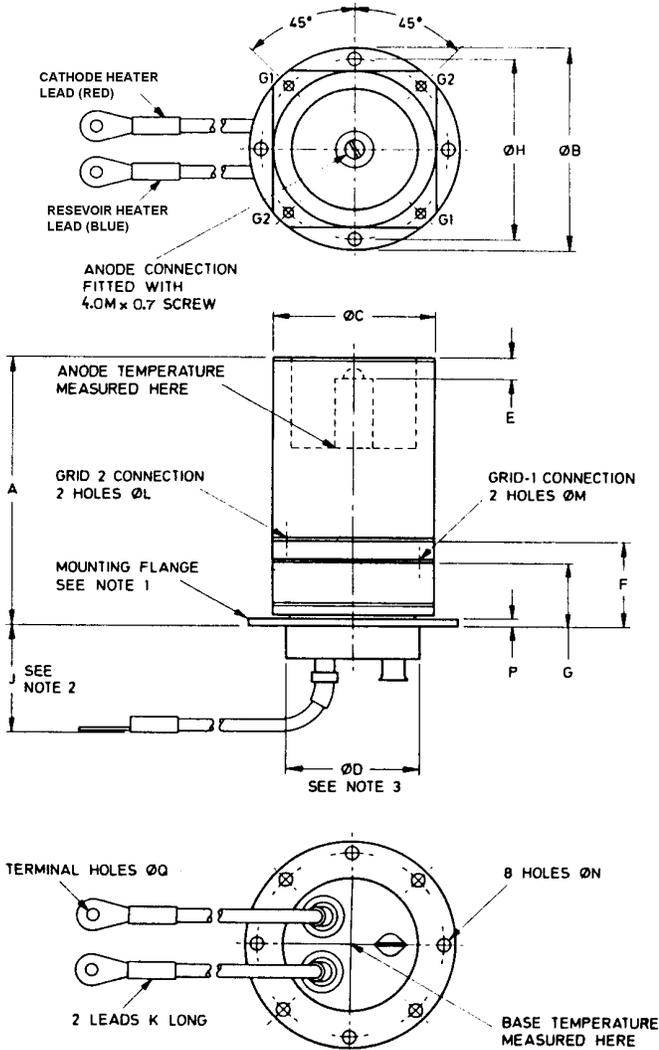
### **X-Ray Radiation**

All high voltage devices produce X-rays during operation and may require shielding. The X-ray radiation from hydrogen thyatrons is usually reduced to a safe level by enclosing the equipment with metal panels.



PT1164

# Hydrogen Thyatron



Ref	Inches	Millimeters
A	3.000 max	76.20 max
B	2.438 max	61.91max
C	1.750 ± 0.031	44.45 ± 0.79
D	1.437	36.50
E	0.225 ± 0.025	5.72 ± 0.64
F	0.940	23.88
G	0.658	16.71
H	2.080 ± 0.070	52.83 ± 1.78
J	1.250 min	31.75 min
K	6.000	152.4
L	0.120	3.05
M	0.120	3.05
N	0.165	4.19
P	0.100	2.54
Q	0.165	4.19

Millimeter dimensions have been derived from inches

## Outline notes

1. The mounting flange is the connection for the cathode, cathode heater and reservoir heater return.
2. A minimum clearance of 1.250 inches (31.75mm) must be allowed below the flange.
3. The recommended mounting hole is 1.500 (38.10mm) diameter.